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Sample questions asked in the 4th edition of System Dynamics: Consider the system shown in Figure 1. It is desired to design a PID controller  $G_c(s)$  such that the dominant closed-loop poles are located at  $s = -1 \pm j1$ . For the PID controller, choose  $a = 0.5$ , and then determine the values of  $K$  and  $b$ . Draw a root

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locus plot with MATLAB. Figure 1 PID-controlled system.

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